# Stochastic Petri Nets

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### Probability Theory Refresher

Set of events is exhaustive if they cover the entire sample space. Events are mutually exclusive if they cannot co-occur.

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Conditional probability 
$$P(A|B) = \frac{P(AB)}{P(B)}$$
  
Statistical independence  $P(AB) = P(A) \cdot P(B)$   
Theorem of total probability  $P(B) = \sum_{i=1}^{n} P(A_i B)$   
 $P(B) = \sum_{i=1}^{n} P(A_i B)$   
 $P(B) = \sum_{i=1}^{n} P(B_i) \cdot P(A_i)$   
Random variables and their moments  $i=1$   
 $P(B) = \sum_{i=1}^{n} P(B|A_i) \cdot P(A_i)$   
Geometrie unable  
 $P_X(k) = (1-p)^{k-1} p$   
Exponentally distributed unable  $(ionk.)$   
Formal Methods in Algorithmic Cheminformatics and Systems Biology  
 $P(E) = f_X(x) = A e^{-Ax}$   $F_X(x) = P(X = x) = \int_{f_X}^{2/16} dx = 1 - e^{-Ax}$   
 $P(B) = biblicly densible function communities clisteriobantism function
 $E(X) = \frac{1}{A} = \int_{X}^{X} \cdot f_X(x) dx$   
 $Variance (2nd central moment)$   
 $f_X^2 = E(X^2) - (E(X))^2$$ 

## Stochastic Process

A family of random variables  $\{X(t)\}$  each with the same set of possible values. State set  $S = \{1, 2, ..., \}$ 

Classification on state space:

Continuous;

Classification on time:

· Continuous; more used

Classification on the nature of the joint probability distribution function.

4 Murhov processes

Markov Chains  
Markov property:  

$$P(X(t) = j|X(t_n) = i_n, \dots, X(0) = i_0) = P(X(t) = j|X(t_n) = i_n)$$
  
 $t > t_n > t_0$   
 $t > t_n > t_0$   
A Markov chain is homogeneous iff:  
 $i_0 + i_0$   
 $t_{herc}$   
 $t_{herc}$   

$$P(X(t+s) = j | X(u+s) = i) = P(X(t) = j | X(u) = i)$$
  
$$t \ge u \qquad s \ge 0$$

Discrete Time Markov Chains

$$P(X_{n+1} = i_{h+1} | X_{n} = i_{n+1} X_{n-1} = i_{n-1} - i_{X_{0}} = i_{0}) =$$

$$= \frac{P(X_{n+1} = i_{n+1} | X_{n} = i_{n})}{P_{ij}(n_{1}n+1)} = P(X_{n+1} = j_{1} | X_{n} = i)$$

$$P_{ij}(n_{1}n+1) = P(X_{n+1} = j_{1} | X_{n} = i)$$

$$P_{ij}(n) = P(X_{n+n} = j_{1} | X_{n} = i)$$

$$P_{ij}(m) = P(X_{n+m} = j_{1} | X_{n} = i)$$

$$P_{ij}(m) = P(X_{n+m} = j_{1} | X_{n} = i)$$

$$P_{i}(N_{i}| + i \in S \sum_{j \in S} P_{ij}(m) = 1$$

$$P(X_{n+m} = j_{j} | X_{n} = i) = \sum_{k \in S} P(X_{n+m} = j_{k} | X_{n+m} = i)$$

$$m \equiv r \ge 0$$

$$P(X_{n+m} = j_{k} | X_{n} = i) = \sum_{k \in S} P_{kj}(m-r) \cdot P_{ik}(r)$$

$$P_{ij}(m) = \sum_{k \in S} P_{kj}(m-r) \cdot P_{ik}(r)$$

### Time-Based State Distribution

Probability of being in a state j at time (step) m.

$$\widetilde{u}_{j}(m) = P(X_{m}=j)$$

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$$T_{ij}(0) = initial distribution$$

$$\sum_{i \in S} T_{i}(0) \cdot P_{ij}(m) = \sum_{i \in S} P(X_0 = i) \cdot P(X_m = j|X_0 = i) =$$

$$= P(X_m = j) = T_{ij}(m)$$

$$T_{i}(m) = T_{i}(0) P^{m}$$

#### Structural Classifications of Markov Chains

Two states **communicate** iff there exist directed paths between them.

The class of a state i is the set of all states which communicate with i.

A Markov chain is irreducible if it consists of a single class.

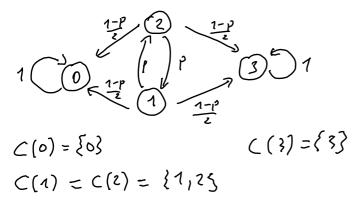
A class C is **transient** if there exists a non-zero one-step transition probability leading out of C.

A class C is **ergodic** if any path starting in C, remains in C.

$$\forall i \in C, \sum_{j \in C} pij = 1$$

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## Recurrence Classification of Markov Chains

Let  $f_j(m)$  be the probability of leaving a state j and first returning in m steps. Then the probability of ever returning to j is:

$$f_j = \sum_{m=1}^{\infty} f_j(m)$$

The state *j* is:

- Transient if  $f_j < 1$ ;
- Recurrent if  $f_j = 1$ ;
- Periodic if the return is only possible at steps  $\nu, 2\nu, 3\nu, \ldots$  where  $\nu$  is the largest such integer;

Additionally, a recurrent state can be:

- null recurrent if  $M_j = \infty$ ;
- positive (non-null) recurrent if  $M_j < \infty$ ;

Mean recurrence time  

$$M_{j} = \sum_{m=1}^{\infty} m. f_{j}(m)$$

## Steady State Distribution

In an irreducible DTMC, all states are:

- transient;
- null recurrent;
- positive recurrent;

And if periodic, then all states have the same period.

$$\sum_{ij=1}^{ij} \sum_{m \to \infty} P(X_{m-j})$$

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In an irreducible, aperiodic (and homogeneous) MC, the limit probabilities exist, are independent of the initial distribution and:

- all states are, either, transient or null recurrent and ∀j ∈ S, π<sub>j</sub> = 0 (there exists no steady state distribution);
- all states are positive recurrent and  $\forall j \in S, \pi_j = \frac{1}{M_i}$ ;

$$\sum_{i \in S} \pi_i = 1$$
  
$$\forall j \in S \sum_{i \in S} \pi_i \cdot P_i = \pi_i \approx \pi_i P = \pi$$

$$Y_i(w)$$
.- Time spent in state i over an interval of  
length m  
 $E(T_i) = T_i \cdot m$   
mean time spent in state i in-between two successive  
visits to state j  
 $Y_{ij} = \frac{T_i}{T_j}$ 

## Absorbing Chains

Order the states so that the absorbing states are first, followed by the transient ones.

$$P = \begin{pmatrix} I & 0 \\ R & Q \end{pmatrix} \qquad P^{n} = \begin{pmatrix} I & 0 \\ R \cdot \tilde{Z} \cdot Q^{n-1} & Q^{n} \end{pmatrix}$$

$$R \left( I + Q + Q^{2} + \dots + Q^{n-1} \right)$$

$$n \to \infty \implies Q^{n} \to 0$$

$$\sum_{i=1}^{n} Q^{i-1} \to (1-Q)^{-1} = N$$
fundamental matrix of the Tic

#### Time before absorption

Starting from state i, let  $v_{ij}$  be the number of visits to state j before an absorbing state is reached. Kronecher delta Function

 $S_{ii} = 1$ 

Sij=0 itj

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 $E(v_{ij}) = n_{ij} \qquad E(v_{ij}) = \delta_{ij} + \sum_{k \in S_{t}} q_{ik} \cdot E(v_{kj})$   $M = \left[ E(v_{ij}) \right]$   $M = I + Q \cdot M$  M - Qn = I (I - Q)n = I  $M = (I - Q)^{-1} = N$ 

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 $v_i = \sum v_{ij}$ 

$$T_{i} = E(v_{i}) = \sum_{j \in S_{t}} E(v_{ij}) = \sum_{j \in S_{t}} u_{ij} \qquad \overrightarrow{T} = [T_{i}]$$

$$\overrightarrow{T} = N. e^{T} \qquad e^{-[T]}$$

$$T = \Pi_{t}(0) \cdot \overrightarrow{T} = \Pi_{t}(0) N \cdot e^{T}$$

$$Aue Lu \ time \ before \ absorption$$

$$\overrightarrow{C^{2}} = (2N - I) \overrightarrow{T} - \overrightarrow{T}_{i}^{2} \qquad \overrightarrow{T}_{i} = [E(v_{i}^{2})]$$

Continuous-time Markov Chains

$$P(X(t) = j | X(t_h) = i_h j X(t_{h-1}) = i_{h-1} \dots j X(t_h) = i_h) = P(X(t) = j | X(t_h) = i_h) = P(X(t) = j | X(t_h) = i_h) = P(X(t) = j | X(t_h) = i_h)$$

$$t > t_h > \dots > t_h \qquad P_{ij}(t_h) = P(X(t_h) = j | X(t_h) = i_h)$$

$$Chapman-Kolmogorov equations for CTMC \qquad P_{ij}(t_h) = P(X(t_h) = j | X(t_h) = i_h)$$

$$P_{ij}(t_h) = \sum_{k \in S} P_{jh}(u_h) P_{hj}(t_{h-1}) \qquad P_{ij}(0) = \begin{cases} 1 & i_h = j \\ 0 & i_h = j \end{cases}$$

$$P_{ij}(t_h) = \sum_{k \in S} P_{jh}(u_h) P_{hj}(t_{h-1}) \qquad P_{ij}(0) = \begin{cases} 1 & i_h = j \\ 0 & i_h = j \end{cases}$$

$$H(t_h) = [P_{ij}(t_h)]$$

$$H(t_h) = H(u_h) \cdot H(t_{h-1})$$

$$H(0) = I$$

$$P_{ij}(t_h) = I$$

$$P_{ij}(t_h) = I$$

$$P_{ij}(t+at) = \sum_{k \in S} P_{ik}(t) \cdot P_{kj}(at) \qquad / - P_{ij}(t)$$

$$P_{ij}(t+at) - P_{ij}(t) = \sum_{k \in S} P_{ik}(t) \cdot P_{kj}(at) - P_{ij}(t) \qquad \sum_{k \in S} P_{ik}(t) \cdot P_{kj}(at)$$

$$P_{ij}(t+at) - P_{ij}(t) = \sum_{k \in S} P_{ik}(t) \left( P_{kj}(at) - P_{kj}(0) \right) / at$$

$$\frac{P_{ij}(t+at) - P_{ij}(t)}{at} = \frac{\sum_{k \in S} P_{ik}(t) \left( P_{kj}(at) - P_{kj}(0) \right)}{at}$$

$$\frac{SH(t)}{st} = H(t). Q$$

$$Q = \lim_{\delta t \to 0} \frac{H(st) - I}{st}$$

$$q_{ij} = \lim_{\delta t \to 0} \frac{P_{ij}(st)}{st}$$

$$q_{ii} = \lim_{\delta t \to 0} \frac{P_{ij}(st)}{st}$$

$$i \neq j$$

Time-Based State Distribution (CTMC)

$$T(t) = P(x(t)=i)$$

$$T(t) = T(0) \cdot H(t)$$

$$\frac{ST(t)}{St} = T(0) \cdot \frac{SH(t)}{St} =$$

$$= \overline{u}(0) \cdot H(t) \cdot Q$$

$$= \overline{u}(t) \cdot Q$$

# Steady State Distribution (CTMC)

The limit probabilities and the steady state distribution exist if the CTMC is irreducible, positive recurrent (and homogeneous).

# Embedded DTMC

A CTMC might reimagined as a DTMC in which the transitions don't happen at equal "unit" intervals, but rather ones sampled from an exponential distribution.

Butore transitioning from i toj we sojowrn  
in i for time Tij, an exponentially distributed  
rundom variable  

$$P(T_{ij} \leq t) = 1 - e^{-q_{ij}t}$$
  $P(T_{ij} > t) = e^{-q_{ij}t}$   
 $T_{min} = Time until any  $h \leq s, h \neq j$  fires  
 $P(T_{min} \leq t) = P(\bigcup_{k \neq i, j} (T_{ik} \leq t)) =$   
 $= 1 - P(\bigcap_{k \neq i, j} (T_{ik} > t))$$ 

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$$= 1 - e^{-\sum_{k \neq i,j} Y_{ik}} + t$$

$$-q_{ji} = \sum_{k=1}^{n} q_{1k} \qquad \sum_{k\neq i,j}^{l} q_{ik} = -q_{ij} - q_{ij}$$

$$P_{\bar{i}j} = \int f_{T_{min}}(t) P(T_{ij} \leq t) dt =$$

$$= -\int (q_{ii} + q_{ij}) e^{(q_{ii} + q_{ij})t} (1 - e^{-q_{1j}t}) dt$$

$$= -q_{ij} + q_{ij} + q_{ij} = e^{(q_{ii} + q_{ij})t} + (1 - e^{-q_{1j}t}) dt$$

$$\begin{aligned} \mathcal{T}_{i} &= \text{the sojourn time in statej pirrespective} \\ &\text{of the next transition.} \\ \\ \mathcal{P}_{j} &= \lim_{t \to \infty} P(\mathbf{X}(t) = j) \\ \\ \mathcal{P}_{j} &= \frac{\pi_{j} E(\tau_{j})}{\sum_{i=S} \pi_{i} E(\tau_{i})} = \text{where II is the steady} \\ &\text{state distribution of} \\ &\text{the embedded DTMC} \\ \\ &= \frac{\pi_{i}}{\sum_{i=S}^{1} \pi_{i} - \frac{1}{-\eta_{ii}}} \end{aligned}$$

#### Stochastic Petri Nets

A stochastic Petri net is composed of a Petri net  $(N, M_0)$  and a collection  $\Lambda = (\lambda_1, \ldots, \lambda_m)$  of, possibly marking dependent, transition rates of each transition  $t_i \in |T|$ .

